

# PENDAHULUAN

- Konsep Dasar Dinamika
- Besaran Dan Sistem Satuan
  - Trigonometri
  - Operasi Vektor

---

Oleh: Achmad Arifin, M.Eng

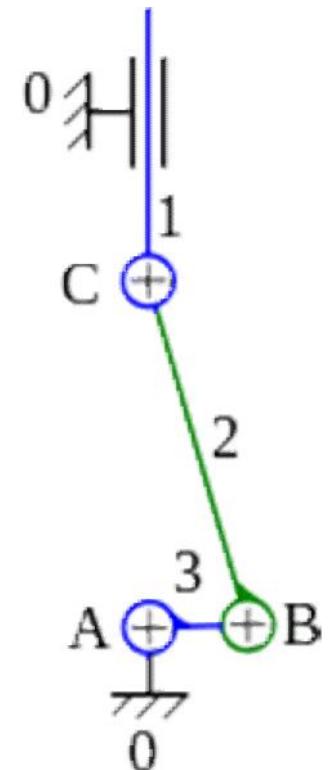


# KONSEP DASAR DINAMIKA



# Konsep Dasar Kinematika & Dinamika Mesin

- Ilmu yang mempelajari pergerakan-pergerakan suatu mesin dan komponennya.
- Membicarakan seputar masalah kecepatan dan percepatan link dari suatu mesin atau mekanisme, dengan batasan-batasan tertentu.



## Konsep Dasar

### Kinematika & Dinamika Mesin

- **Kinematika** → mempelajari pergerakan link dari suatu mekanisme dengan secara grafis, tanpa mempertimbangkan dari mana asal pergerakan link tersebut diperoleh.
- **Dinamika** → mempelajari pergerakan link dari suatu mekanisme dengan secara analisis (hitungan) dengan mempertimbangkan darimana asal pergerakan link tersebut diperoleh.



## 1.6 General Procedure for Analysis

The most effective way of learning the principles of engineering mechanics is to *solve problems*. To be successful at this, it is important to always present the work in a *logical* and *orderly manner*, as suggested by the following sequence of steps:

- Read the problem carefully and try to correlate the actual physical situation with the theory studied.
- Tabulate the problem data and draw any necessary diagrams.
- Apply the relevant principles, generally in mathematical form. When writing any equations, be sure they are dimensionally homogeneous.
- Solve the necessary equations, and report the answer with no more than three significant figures.
- Study the answer with technical judgment and common sense to determine whether or not it seems reasonable.



## TAHAP-TAHAP PROSES PERENCANAAN MEKANISME

1. Pengenalan problem yang dirancang.
2. Konsep mekanisme yang dirancang dalam bentuk sederhana (skema atau bagan mekanisme).
3. Analisa kinematis atau tinjauan karakteristik gerakan mekanisme berdasarkan bentuk geometris mekanisme secara murni, yang mungkin nantinya membutuhkan modifikasi mekanisme.
4. Analisa statis atau penentuan sifat dan besar gaya – gaya yang terjadi akibat gerak utama mekanisme.
5. Pemilihan bahan yang sesuai dengan hasil perhitungan dengan memperhatikan faktor ekonomis.
6. Analisa dinamika atau penentuan gaya – gaya inersia dan akibatnya terhadap keselamatan, serta memenuhi persyaratan operasional mekanisme.



# BESARAN DAN SISTEM SATUAN



## BESARAN DAN SISTEM SATUAN

No	<i>Besaran Fisik</i>	<i>Vektor (V) atau Skalar (S)</i>	<i>Simbol</i>	<i>Satuan</i>	
				<i>BS</i>	<i>SI</i>
1.	<i>Jarak (Displacement)</i>	<i>V</i>	<u>s</u> , <u>x</u>	<i>in</i>	<i>m</i>
2.	<i>Waktu (Time)</i>	<i>S</i>	<u>t</u>	<i>sec</i>	<i>sec</i>
3.	<i>Gaya (Force)</i>	<i>V</i>	<u>F</u> , <u>R</u>	<i>lb</i>	<i>N</i>
4.	<i>Kecepatan (Velocity)</i>	<i>V</i>	<u>v</u>	<i>in/sec</i>	<i>m/sec</i>
5.	<i>Percepatan (Acceleration)</i>	<i>V</i>	<u>a</u>	<i>in/sec<sup>2</sup></i>	<i>m/sec<sup>2</sup></i>
6.	<i>Jarak Sudut (Angular Displacement)</i>	<i>V</i>	<u>θ</u> , <u>φ</u>	<i>rad</i>	<i>rad</i>
7.	<i>Kecepatan Sudut (Angular Velocity)</i>	<i>V</i>	<u>ω</u>	<i>rad/sec</i>	<i>rad/sec</i>
8.	<i>Percepatan Sudut (Angular Acceleration)</i>	<i>V</i>	<u>α</u>	<i>rad/sec<sup>2</sup></i>	<i>rad/sec<sup>2</sup></i>
9.	<i>Massa (Mass)</i>	<i>S</i>	<u>m</u>	<i>lb.sec<sup>2</sup>/in</i>	<i>N.sec<sup>2</sup>/m</i>
10.	<i>Momentum Linier (Linear Momentum)</i>	<i>V</i>	<u>Z</u>	<i>lb.sec</i>	<i>N.sec</i>
11.	<i>Torsi (Torque)</i>	<i>V</i>	<u>T</u>	<i>lb.in</i>	<i>N.m</i>
12.	<i>Kerja (Work)</i>	<i>S</i>	<u>W</u>	<i>lb.in</i>	<i>N.m</i>
13.	<i>Enersi (Energy)</i>	<i>V</i>	<u>E</u>	<i>lb.in</i>	<i>N.m</i>

### Catatan :

1. Tabel di atas dibuat berdasarkan *F*, *t* dan *s* sebagai satuan dasar.
2. Simbol dengan tanda garis bawah menandakan besaran vektor.
3. Simbol tanpa garis bawah menandakan besaran skalar.



## BESARAN DAN SISTEM SATUAN

<i>Awalan</i>	<i>Singkatan</i>	<i>Nilai</i>
<i>Tera</i>	<i>T</i>	$10^{12}$
<i>Giga</i>	<i>G</i>	$10^9$
<i>Mega</i>	<i>M</i>	$10^6$
<i>Kilo</i>	<i>k</i>	$10^3$
<i>Hektar</i>	<i>h</i>	$10^2$
<i>Deka</i>	<i>da</i>	$10^1$
<i>Desi</i>	<i>d</i>	$10^{-1}$
<i>Centi</i>	<i>c</i>	$10^{-2}$
<i>Mili</i>	<i>m</i>	$10^{-3}$
<i>Mikro</i>	$\mu$	$10^{-6}$
<i>Nano</i>	<i>n</i>	$10^{-9}$
<i>Piko</i>	<i>p</i>	$10^{-12}$
<i>Femto</i>	<i>f</i>	$10^{-15}$



## KONVERSI SATUAN

DINAMIKA MESIN

<b>VOLUME</b>	$1 \text{ liter} = 1000 \text{ cm}^3 = 10^{-3} \text{ m}^3$
<b>PERCEPATAN</b>	$1 \text{ ft/s}^2 = 0,3048 \text{ m/s}^2$
<b>PANJANG</b>	$1 \text{ A} = 1 \times 10^{-10} \text{ m}$ $1 \text{ ft} = 0,3048 \text{ m}$ $1 \text{ in} = 2,54 \times 10^{-2} \text{ m}$ $1 \text{ mile} = 1609 \text{ m}$ $1 \text{ mil} = 2,54 \times 10^5 \text{ in}$ $1 \text{ ft} = 12 \text{ in}$
<b>GAYA</b>	$1 \text{ dyne} = 10^{-5} \text{ N}$ $1 \text{ lb} = 4,448 \text{ N}$
<b>DAYA</b>	$1 \text{ BTU/s} = 1054 \text{ W}$ $1 \text{ kal/s} = 4,184 \text{ W}$ $1 \text{ ft.lb/s} = 1,356 \text{ W}$ $1 \text{ hp} = 746 \text{ W}$
<b>ENERGI</b>	$1 \text{ BTU} = 1054 \text{ Joule}$ $1 \text{ kal} = 4,184 \text{ Joule}$ $1 \text{ erg} = 10^{-7} \text{ Joule}$ $1 \text{ ft.lb} = 1,356 \text{ Joule}$ $1 \text{ kWh} = 3,6 \times 10^6 \text{ Joule}$



## Faktor Konversi dari satuan US ke SI

1 Cubic inch (in <sup>3</sup> )	=	16.387	Cubic centimeters (cc)
1 Foot (ft)	=	0.3048	Meters (m)
1 Horsepower (hp)	=	745.699	Watts (W)
1 Inch (in)	=	0.0254	Meters (m)
1 Mile	=	1609.344	Meters (m)
1 Pound force (lb)	=	4.4482	Newton (N)
1 Pound mass (lbf)	=	0.4536	Kilograms (kg)
1 Pound foot (lb-ft)	=	1.3558	Newton-meters (N-m)
	=	1.3558	Joules (J)
1 Pound-foot/second (lb-ft/s)	=	1.3558	Watts (W)
1 Pound-inch (lb-in)	=	0.1128	Newton-meters (N-m)
	=	0.1128	Joules (J)
1 Pound-inch/second (lb-in/s)	=	0.1128	Watts (W)
1 Revolution/minute (rpm)	=	0.1047	radians/second (rad/sec)



## BESARAN DAN SISTEM SATUAN

**Rules for Use.** Here are a few of the important rules that describe the proper use of the various SI symbols:

- Quantities defined by several units which are multiples of one another are separated by a *dot* to avoid confusion with prefix notation, as indicated by  $N = \text{kg} \cdot \text{m/s}^2 = \text{kg} \cdot \text{m} \cdot \text{s}^{-2}$ . Also,  $\text{m} \cdot \text{s}$  (meter-second), whereas  $\text{ms}$  (milli-second).
- The exponential power on a unit having a prefix refers to both the unit *and its prefix*. For example,  $\mu\text{N}^2 = (\mu\text{N})^2 = \mu\text{N} \cdot \mu\text{N}$ . Likewise,  $\text{mm}^2$  represents  $(\text{mm})^2 = \text{mm} \cdot \text{mm}$ .
- With the exception of the base unit the kilogram, in general avoid the use of a prefix in the denominator of composite units. For example, do not write  $\text{N/mm}$ , but rather  $\text{kN/m}$ ; also,  $\text{m/mg}$  should be written as  $\text{Mm/kg}$ .
- When performing calculations, represent the numbers in terms of their *base or derived units* by converting all prefixes to powers of 10. The final result should then be expressed using a *single prefix*. Also, after calculation, it is best to keep numerical values between 0.1 and 1000; otherwise, a suitable prefix should be chosen. For example,

$$\begin{aligned}(50 \text{ kN})(60 \text{ nm}) &= [50(10^3) \text{ N}][60(10^{-9}) \text{ m}] \\ &= 3000(10^{-6}) \text{ N} \cdot \text{m} = 3(10^{-3}) \text{ N} \cdot \text{m} = 3 \text{ mN} \cdot \text{m}\end{aligned}$$



1. Hitunglah konversi  $60 \text{ km/jam} \rightarrow \dots \text{m/dt} \rightarrow \dots \text{ft/dt}$



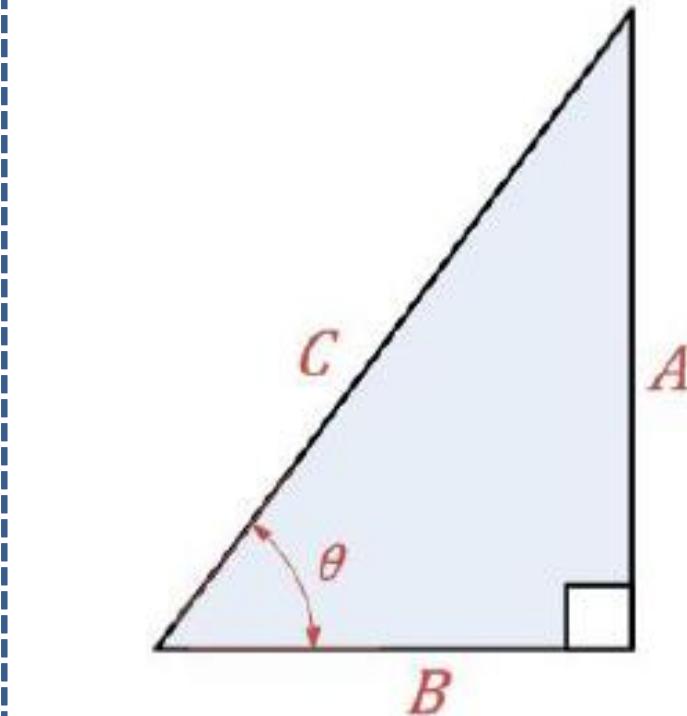
2. Konversikan menjadi satuan SI  
 $300 \text{ lb.s} \dots ?$   
 $52 \text{ slug/ft}^3 \dots ?$



# TRIGONOMETRI



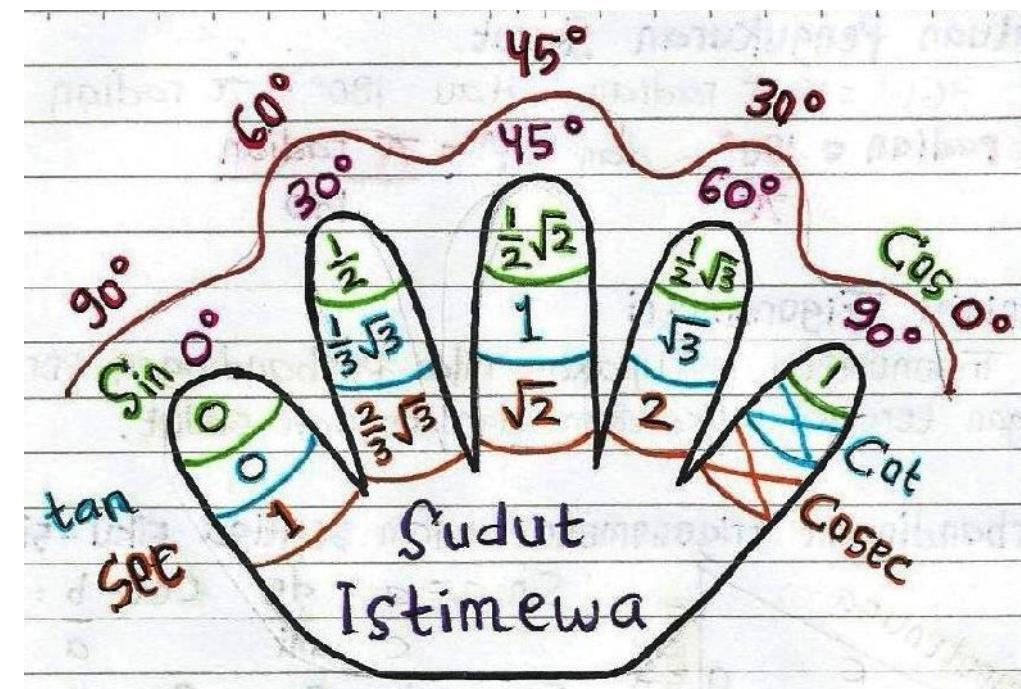
# TRIGONOMETRI

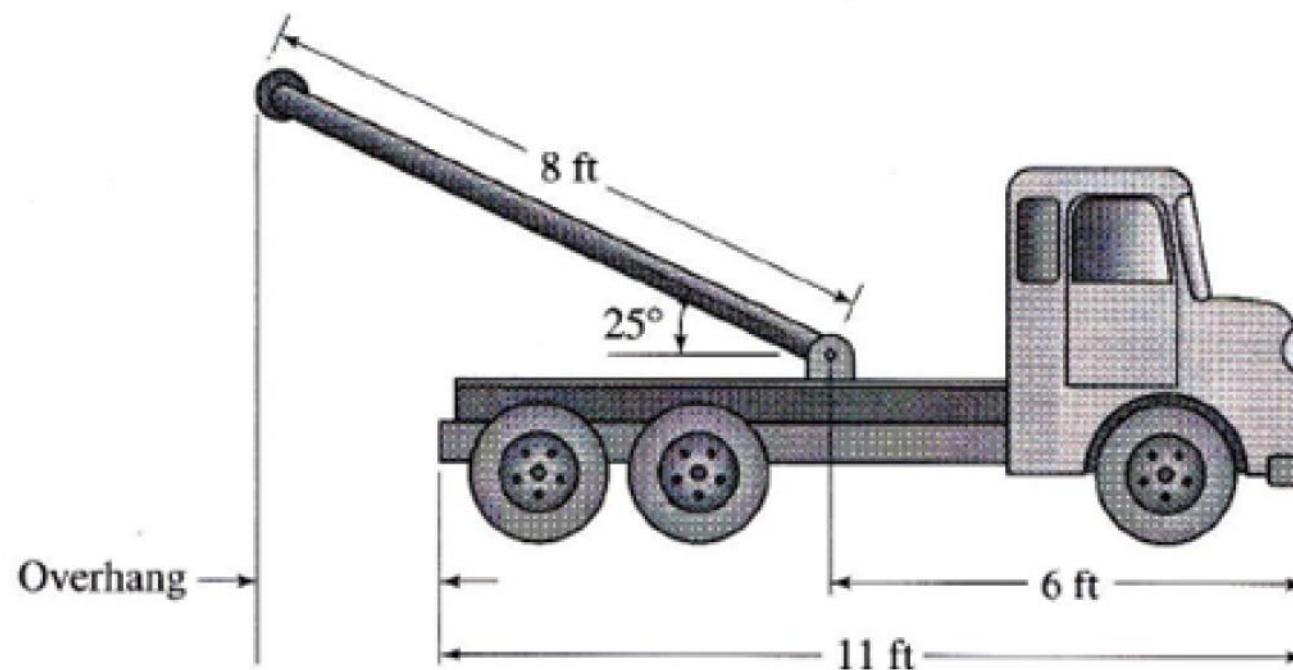


$$\sin = \dots ?$$

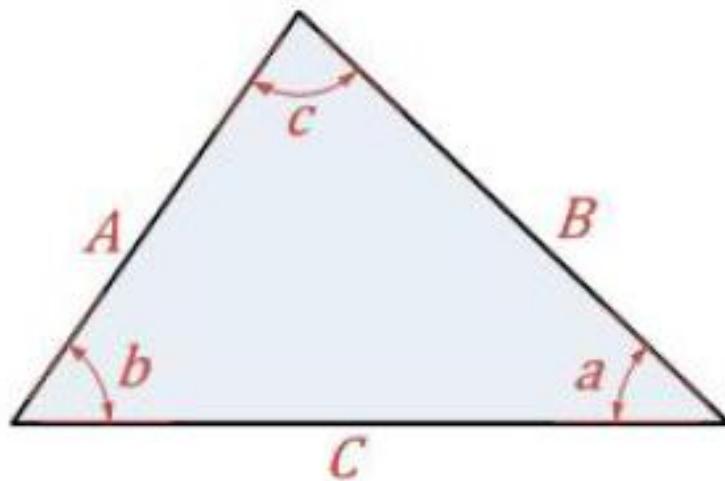
$$\cos = \dots ?$$

$$\tan = \dots ?$$





## ATURAN SINUS COSINUS

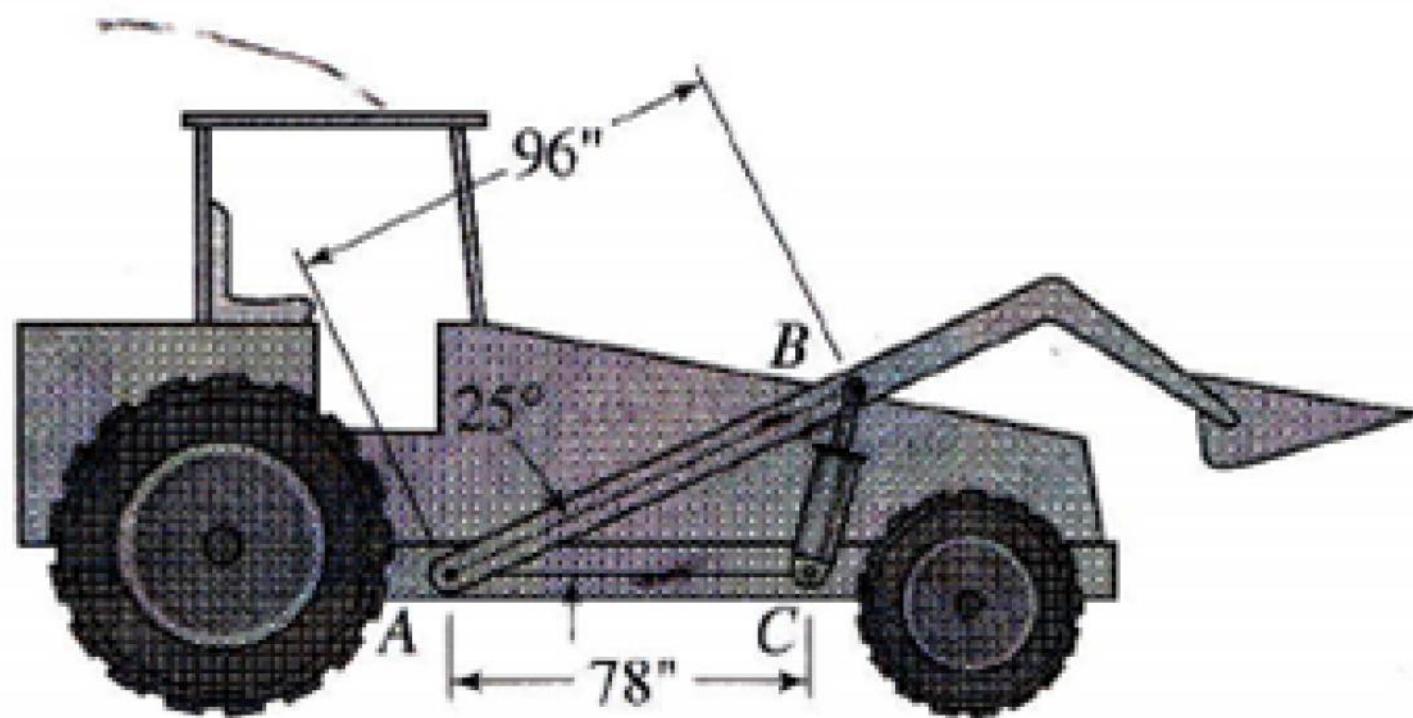


$$\frac{A}{\sin a} = \frac{B}{\sin b} = \frac{C}{\sin c}$$

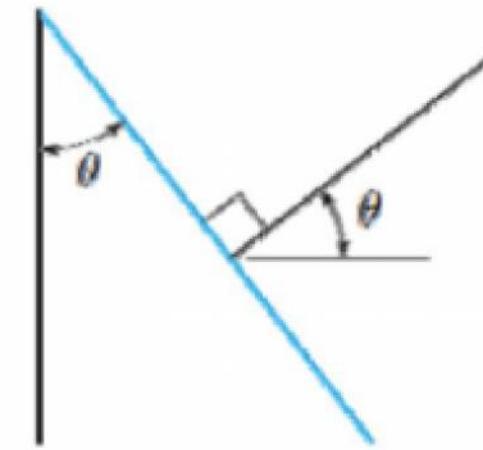
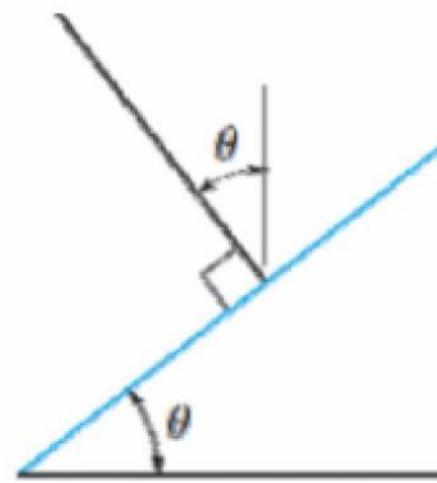
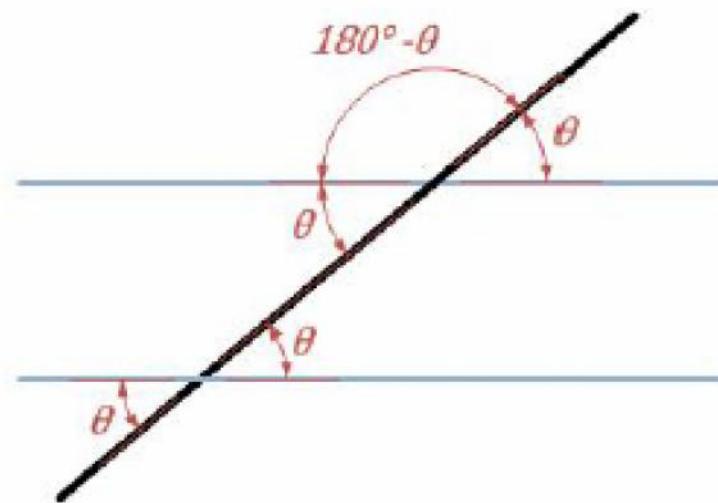
Aturan Cosinus

$$c = \sqrt{A^2 + B^2 - 2AB \cos c}$$





# SUDUT



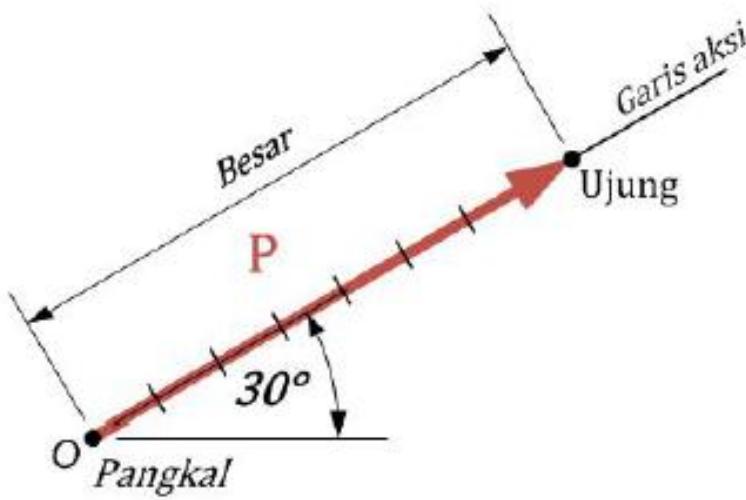
# OPERASI VEKTOR



## OPERASI VEKTOR

- **Skalar** : besaran yang hanya memiliki besar saja (jarak, luas)
- **Vektor** : besaran yang memiliki besar dan arah. (kecepatan, gaya, percepatan)

Vektor dapat dinyatakan dengan sebuah garis lurus dengan arah panah, dimana panjang garis menunjukkan besarnya dalam skala tertentu.

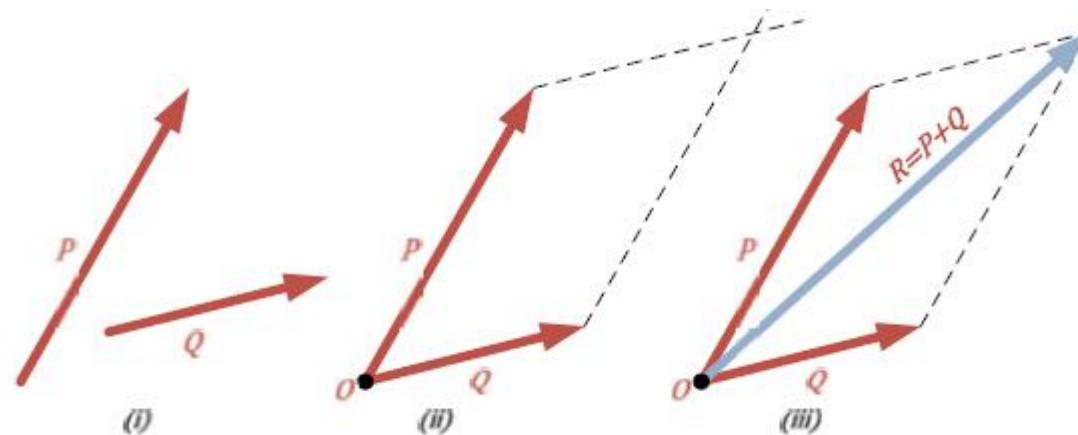


Penulisan dengan cetak tebal **P**,  
atau simbol panah di atas  
vektor  $\vec{P}$

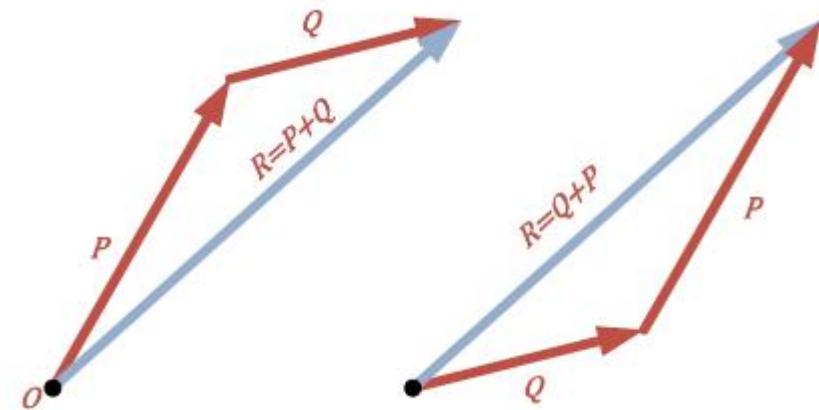


# PENJUMLAHAN VEKTOR

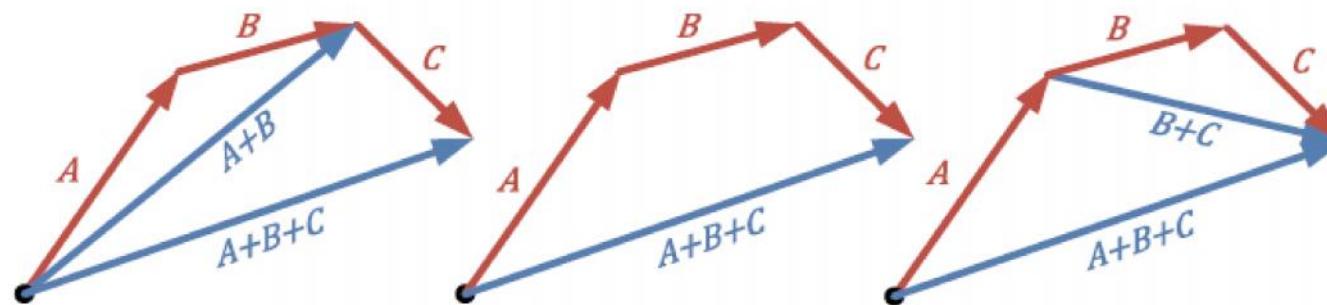
Aturan JajaranGenjang



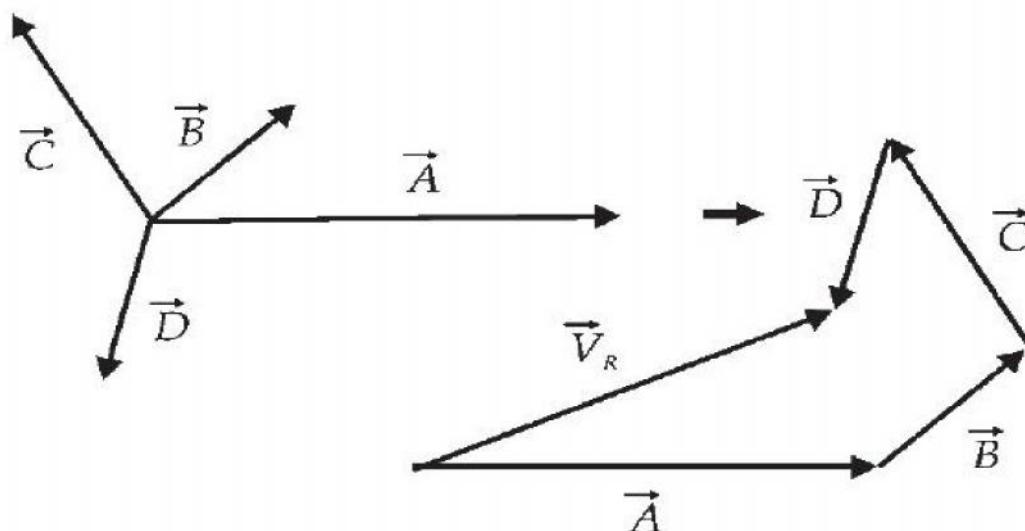
Aturan Segitiga



## PENJUMLAHAN VEKTOR yang SEBIDANG

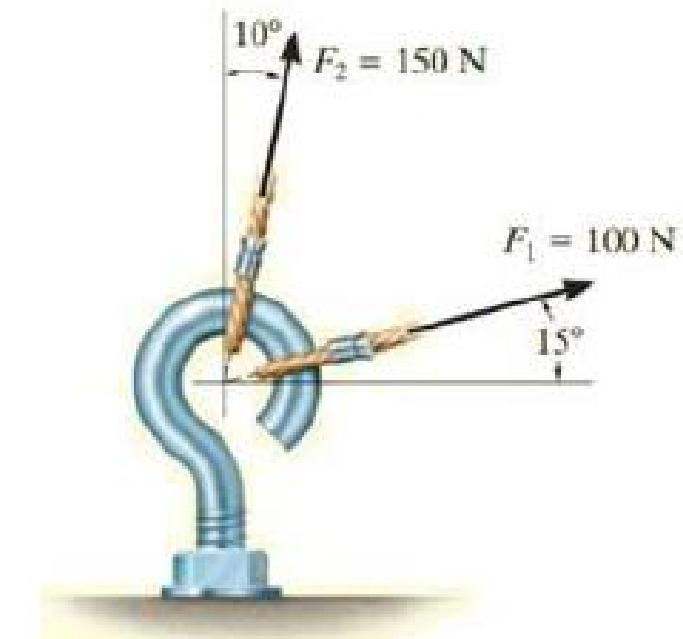
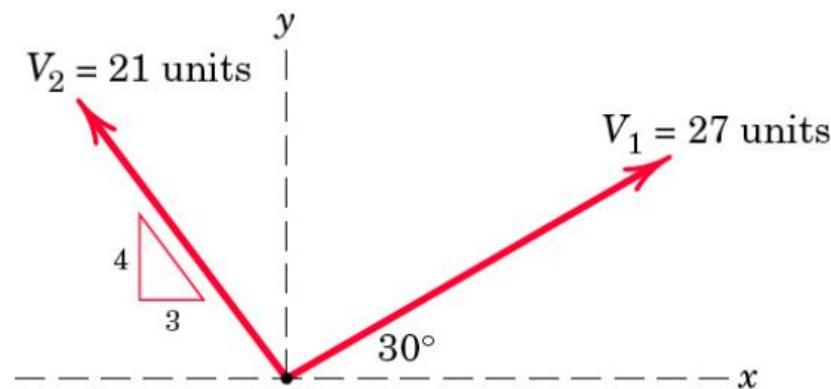


Asosiatif :  $\vec{A} + \vec{B} + \vec{C} = (\vec{A} + \vec{B}) + \vec{C} = \vec{A} + (\vec{B} + \vec{C})$

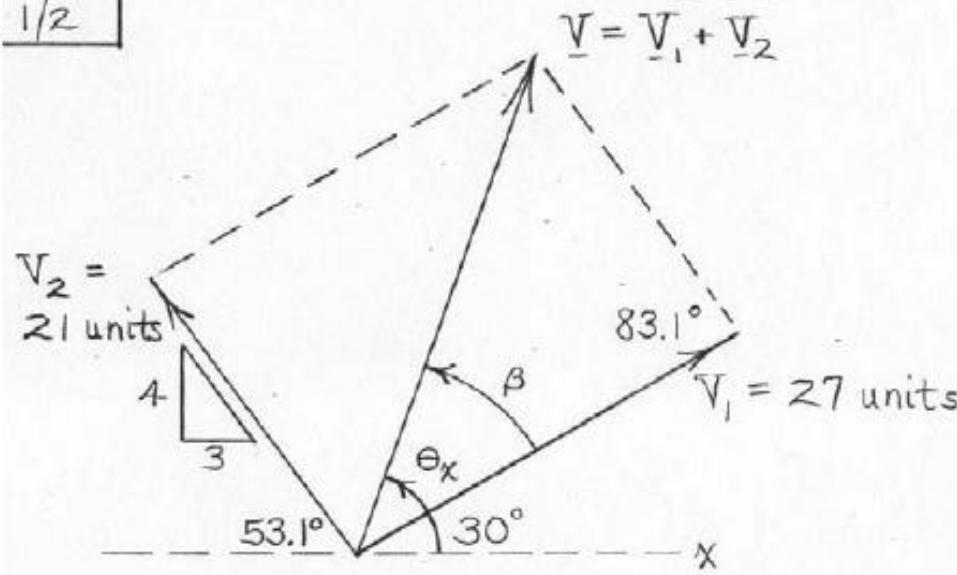


## CONTOH SOAL

Tentukan besar dan arah Resultante, secara **ANALITIS** maupun **GRAFIS.**!



1/2

**Metode Grafis:**

$$V = 32 \text{ unit dan } \theta_x = 70^\circ$$

**Metode Matematis:**

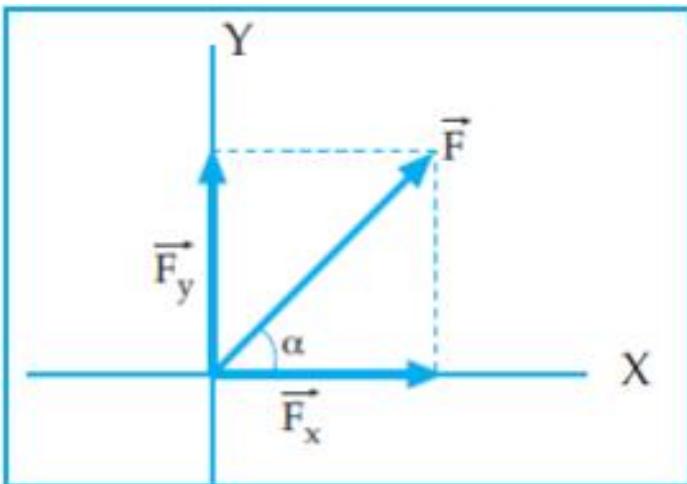
$$V = \sqrt{27^2 + 21^2 - 2 \times 27 \times 21 \times \cos 83,1} = 32,2 \text{ unit}$$

$$\frac{\sin \beta}{21} = \frac{\sin 83,1}{32,2} \rightarrow \beta = 40,4$$

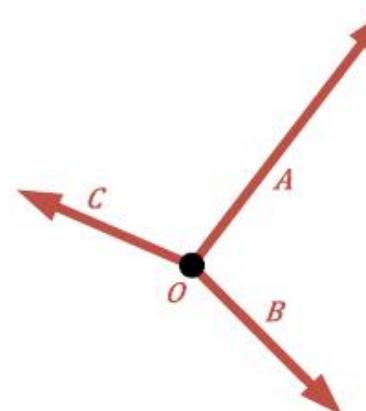
$$\alpha = \beta + 30^\circ = 40,4^\circ + 30^\circ = 70,4^\circ \text{ unit}$$



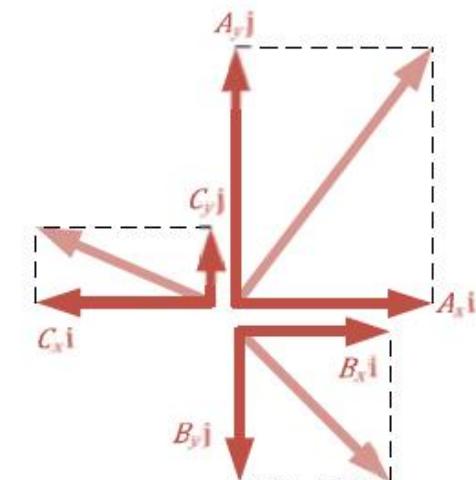
## PENGURAIAN VEKTOR



$$\vec{F}_x = \dots ?$$
$$\vec{F}_y = \dots ?$$



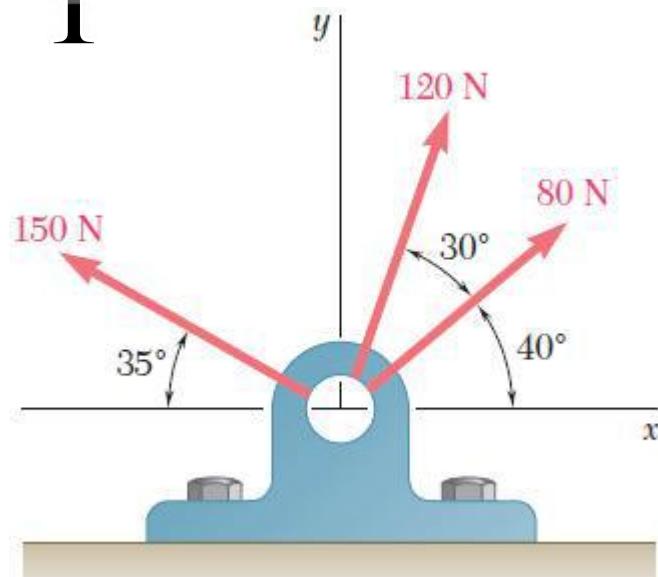
$$\vec{D} = \vec{A} + \vec{B} + \vec{C}$$



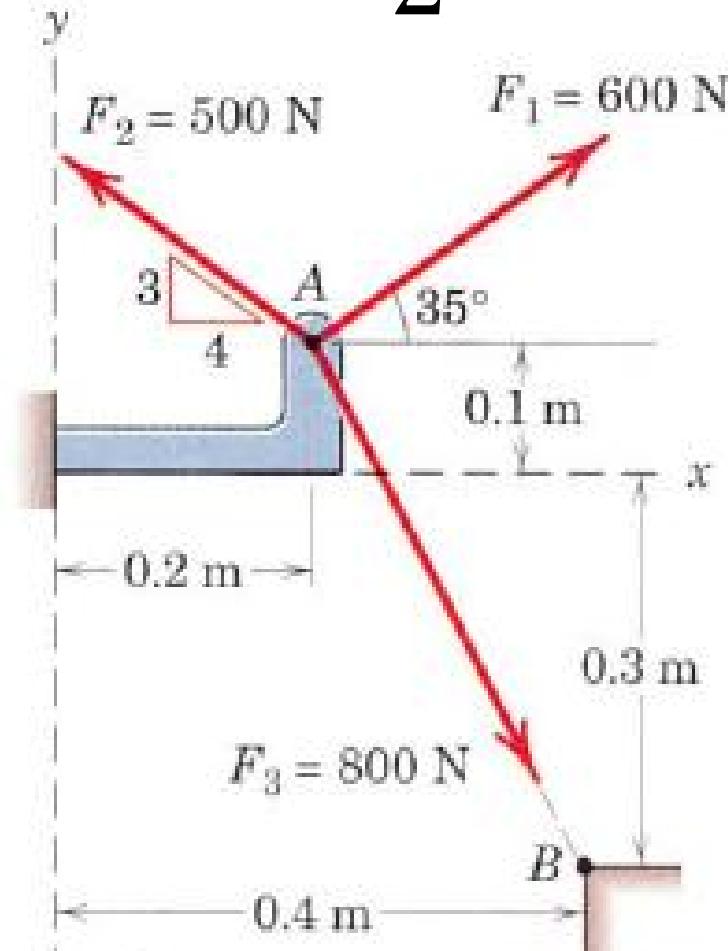
## CONTOH SOAL-2

Tentukan besar dan arah Resultante, secara **ANALITIS...**!

1



2



## Penyelesaian secara analitis

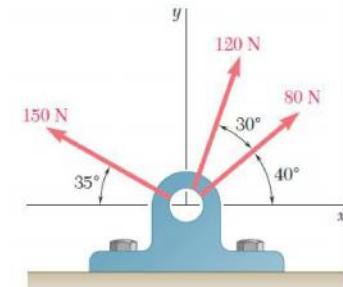
Uraikan masing-masing vektor menjadi komponen-komponen skalar-nya sehingga dapat dijumlahkan

Gaya	Besar Gaya (N)	$\theta$	Komponen x (N) $F \cos \theta$	Komponen y (N) $F \sin \theta$	
$F_1$	80	40	61,3	51,4	
$F_2$	120	70	41,0	112,8	
$F_3$	150	145	-122,9	86,0	
$\Sigma$			$R_x = -20,6$		
				$R_y = 250,2$	

Sehingga besarnya resultan gaya adalah

$$R = \sqrt{R_x^2 + R_y^2} = \sqrt{(-20,6)^2 + 250,2^2}$$

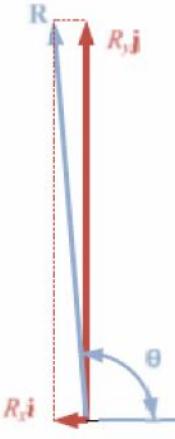
$$\vec{R} = -251,0 \text{ N}$$



Arah dari vektor resultan  $\vec{R}$  dinyatakan dengan sudut  $\theta$  yang besarnya

$$\theta = \arctan \frac{F_y}{F_x} = \arctan \left( \frac{250,2}{-20,6} \right) = \arctan(-12,1)$$

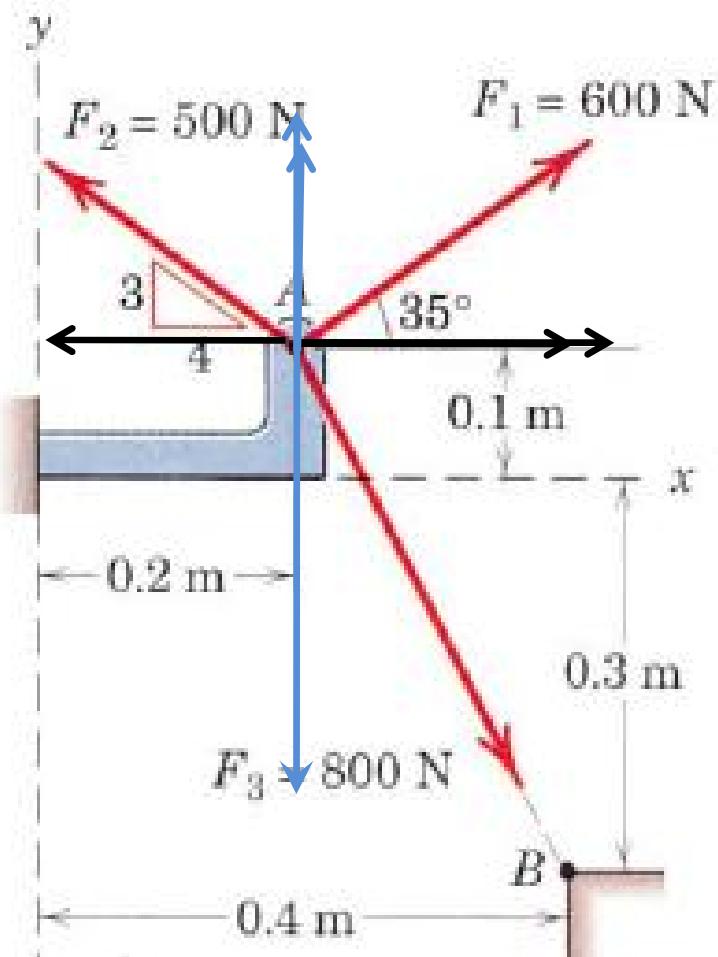
$$\theta = -85,3^\circ$$



Perhatikan pembilang dan penyebut dari fungsi arctan. Harga Sinus positif dan Cosinus negatif menunjukkan kuadaran II. Sehingga sudut  $\theta$  yang sesuai adalah

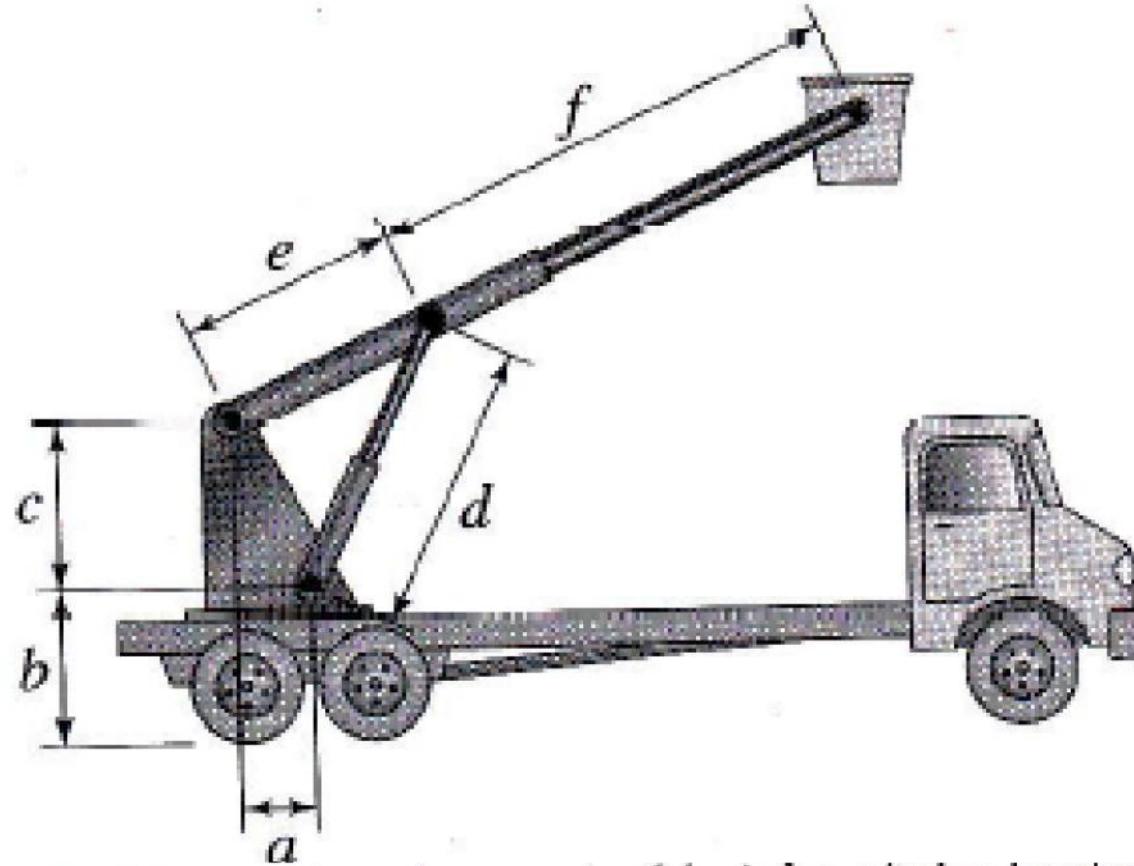
$$\theta = -85,3^\circ + 180^\circ = 94,7^\circ$$

b)  $\Sigma F_x$  dan  $\Sigma F_y$



$$\begin{aligned}\Sigma F_x &= F_{1x} + F_{3x} + F_{2x} \\&= 491 + 358 - 400 \\&= 449 \text{ N}\end{aligned}$$

$$\begin{aligned}\Sigma F_y &= F_{1y} + F_{2y} + F_{3y} \\&= 344 + 300 - 716 \\&= -72 \text{ N}\end{aligned}$$



- 3-18. Determine the vertical height of the basket in Fig. P3.18 when  $a = 24$  in.,  $b = 36$  in.,  $c = 30$  in.,  $d = 60$  in.,  $e = 6$  ft, and  $f = 10$  ft.

- 3-19. For the lift described in Problem 3-18, determine the vertical height of the basket when the hydraulic cylinder is shortened to 50 in.

